

Yesterday: Directional derivatives & the Gradient.

$$D_{\hat{u}} f(a,b) = \underbrace{f_x(a,b)}_{\text{red}} \underbrace{u_1}_{\text{blue}} + \underbrace{f_y(a,b)}_{\text{red}} \underbrace{u_2}_{\text{blue}} \quad \hat{u} \quad \nabla f$$

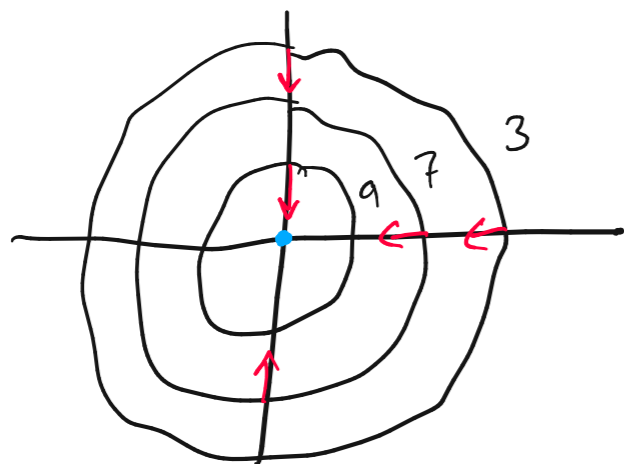
↖ where  $\hat{u} = \langle u_1, u_2 \rangle$  unit vector.

↖ Scalar.

$$\nabla f(x,y) = \langle f_x(x,y), f_y(x,y) \rangle$$

↖ a vector.

Gradient tells us the direction of greatest ascent.



• = Critical point.

• = gradient vectors.

gradient vectors are perpendicular to contours.

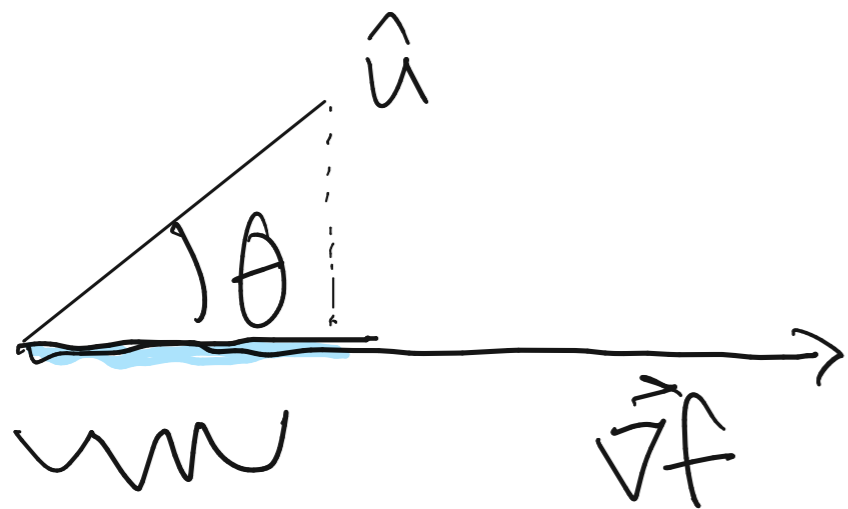
Notice:  $D_{\hat{u}} f(x, y) = \vec{\nabla} f \cdot \hat{u}$

So... recall the dot product (cosine version)

$$\vec{v} \cdot \vec{w} = \|\vec{v}\| \|\vec{w}\| \cos \theta$$

Applying this here, we see:  $\hat{u}$  unit vector!

$$\begin{aligned} D_{\hat{u}} f &= \vec{\nabla} f \cdot \hat{u} = \|\vec{\nabla} f\| \cdot \|\hat{u}\| \cdot \cos \theta \\ &= \|\vec{\nabla} f\| \cos \theta. \end{aligned}$$

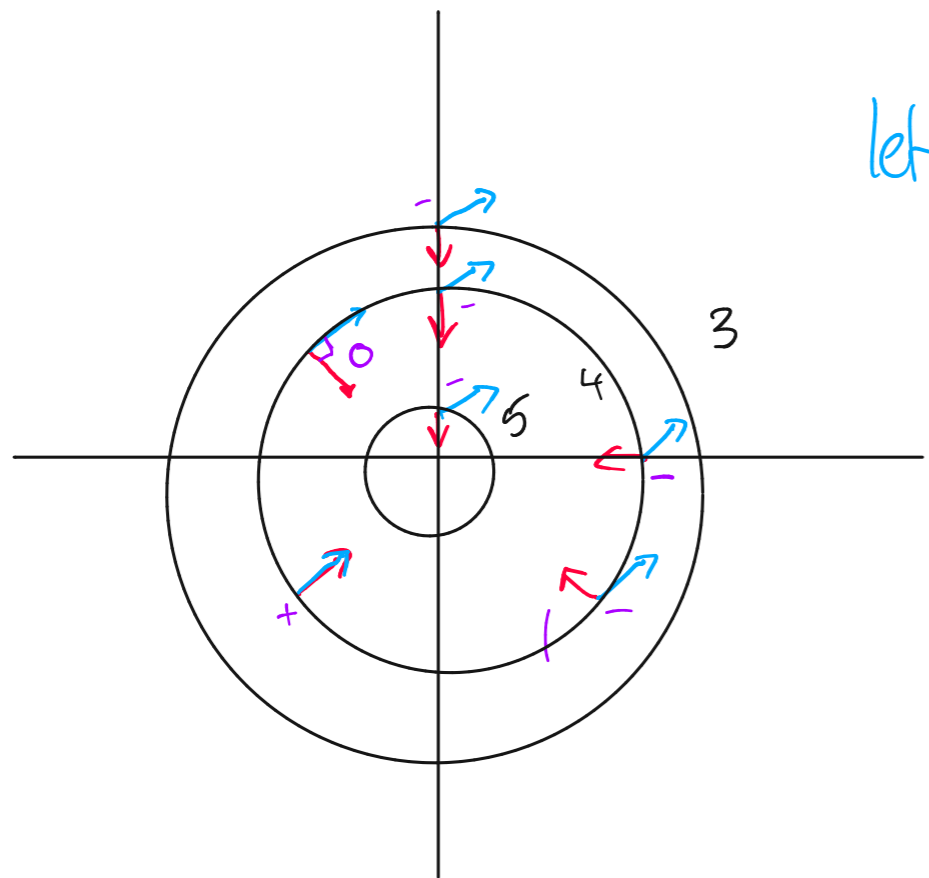


this length  
represents  $D_{\hat{u}} f$ .

$$\begin{aligned} D_{\hat{u}} f &= \vec{\nabla} f \cdot \hat{u} \\ &= \|\nabla f\| \cos \theta. \end{aligned}$$

If  $\hat{u} \perp \nabla f$  then  $D_{\hat{u}} f = 0$ .

This gives us a way to estimate the sign  
of  $D_{\hat{u}} f$  using our geometric intuition



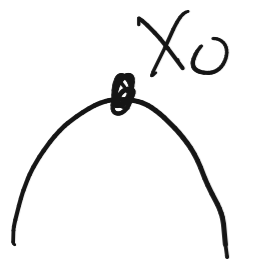
let  $\hat{u} = \langle \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}} \rangle$ .

Purple denote the sign of  $D_{\hat{u}} f(\text{pt.})$ .

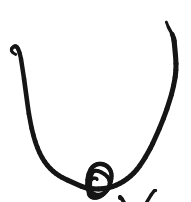
§ 10.7: "Optimization"  $\rightarrow$  "Critical Point theory".

In Calc I, a critical point of a function is an  
 $x$ -value  $x_0$  st  $f'(x_0) = 0$ .

Crit pts come in 2 varieties in 1-D:



local maxes  
 $-x^2$



local mins  
 $+x^2$

This same idea works in functions of two variables!

Def: Let  $f(x,y)$  be a func. of 2 vars

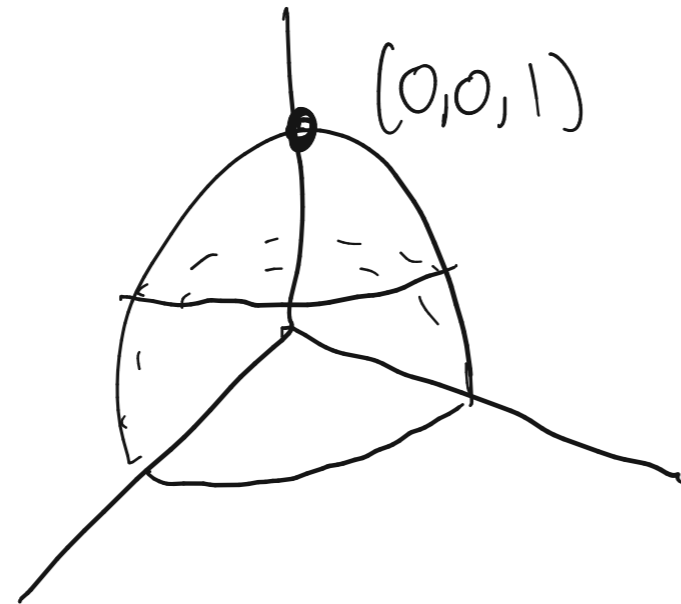
We say that  $(a,b)$  is a critical point

of  $f(x,y)$  if  $\vec{\nabla} f(a,b) = \vec{0}$

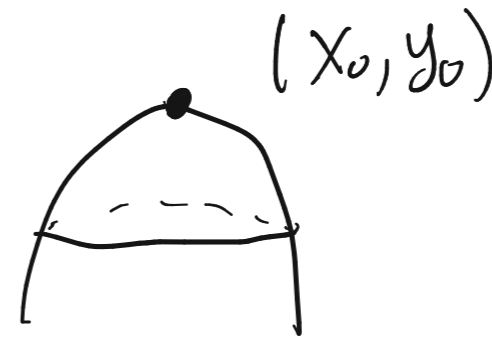
i.e.  $f_x(a,b) = 0$  AND  $f_y(a,b) = 0$ .

Ex Claim is  $f(x,y) = \sqrt{1-x^2-y^2}$  has a critical point @

$(0,0)$



local max.



$$\nabla f = \left\langle \frac{-x}{\sqrt{1-x^2-y^2}}, \frac{-y}{\sqrt{1-x^2-y^2}} \right\rangle$$

$$\nabla f(0,0) = \langle 0, 0 \rangle = \vec{0}$$

So  $(0,0)$  is a Crit. Pt. of  $f(x,y)$ .

# A Gallery of Critical Points:

local max



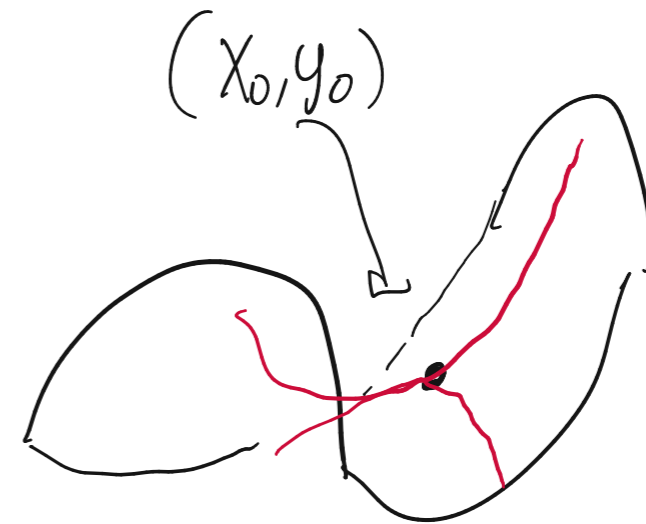
$$\begin{aligned} \text{Ex: } & -x^2 - y^2 \\ & @ (0,0) \end{aligned}$$

local min:



$$\begin{aligned} \text{Ex: } & x^2 + y^2 \\ & @ (0,0) \end{aligned}$$

Saddle Point.

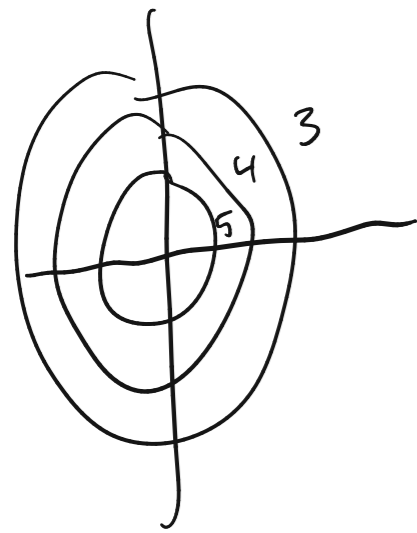


$$\begin{aligned} \underline{\text{Ex:}} & \quad x^2 - y^2 \quad @ (0,0). \end{aligned}$$

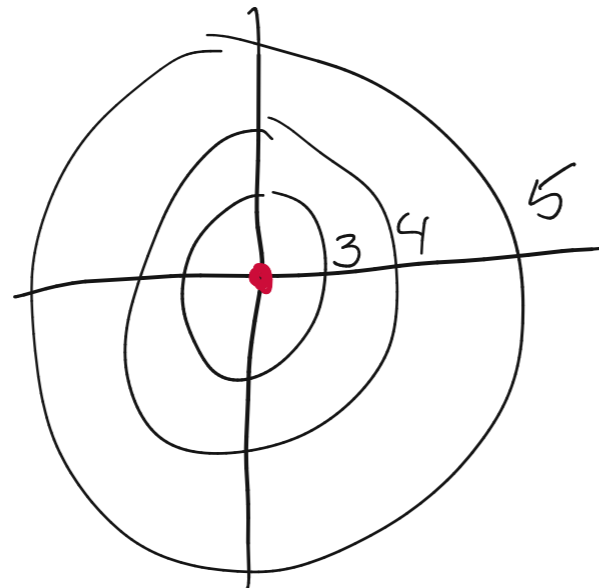


On a Contour Diagram:

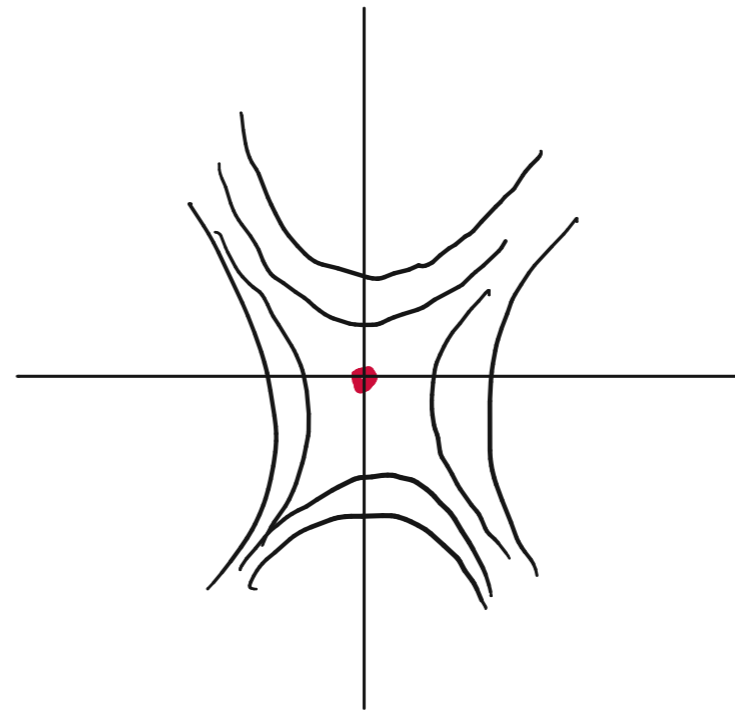
local max



local min



Saddle Point:



## Finding Crit. pts:

Ex  $f(x,y) = 2xy + 4x - 2y + 3.$

Method ① find  $\vec{\nabla} f$

② Set  $\vec{\nabla} f = 0$

③ Solve for your crit pts.

$$\nabla f = \langle 2y + 4, 2x - 2 \rangle = \langle 0, 0 \rangle$$

$$\begin{cases} 2y+4=0 & \Rightarrow y=-2 \\ 2x-2=0 & \Rightarrow x=1. \end{cases}$$

Only crit. pt is @  $(1, -2)$ .

Check:  $\langle 2 \cdot (-2) + 4, 2(1) - 2 \rangle = \langle 0, 0 \rangle$ .

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$\Sigma x$   $f(x, y) = 3x^3 + y^2 - 9x + 4y$

$$\vec{\nabla} f = \langle 9x^2 - 9, 2y + 4 \rangle = \langle 0, 0 \rangle$$

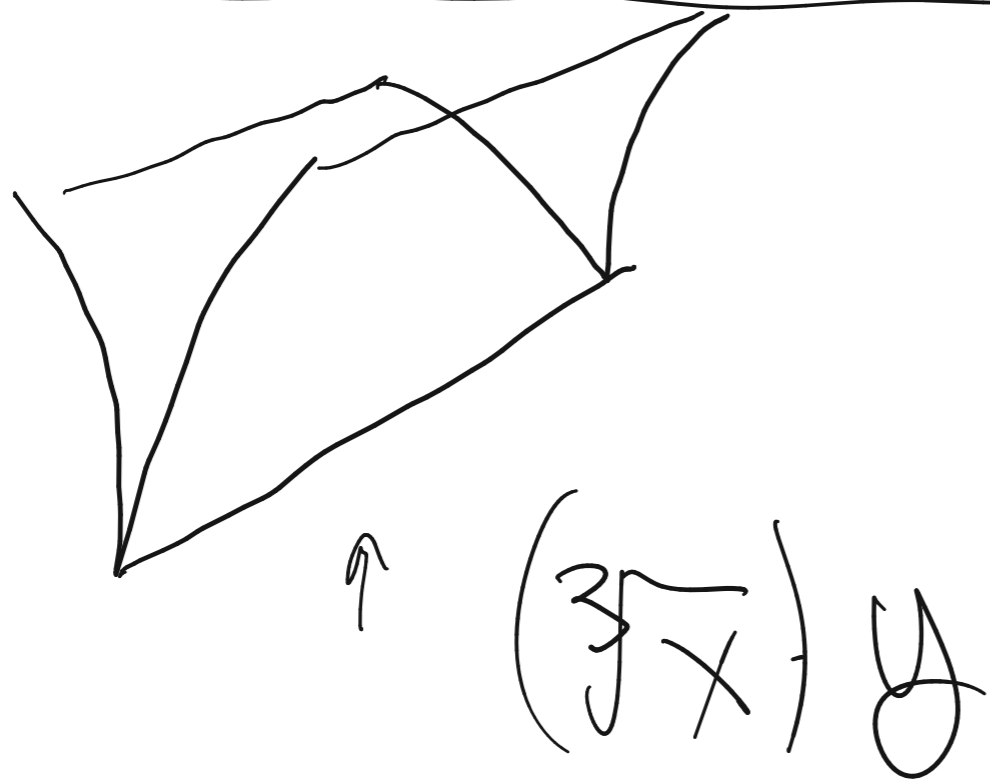
$$\begin{cases} 9x^2 - 9 = 0 \\ 2y + 4 = 0. \end{cases} \Rightarrow \begin{cases} x = \pm 1 \\ y = -2. \end{cases}$$

two potential Crit points:  $(1, -2) \checkmark$   
 $(-1, -2) \checkmark$

$$\vec{\nabla} f(1, -2) = \langle 9 \cdot (1)^2 - 9, 2(-2) + 4 \rangle = \langle 0, 0 \rangle$$

$$\nabla f(-1, -2) = \langle 9(-1)^2 - 9, 2(-2) + 4 \rangle = \langle 0, 0 \rangle$$

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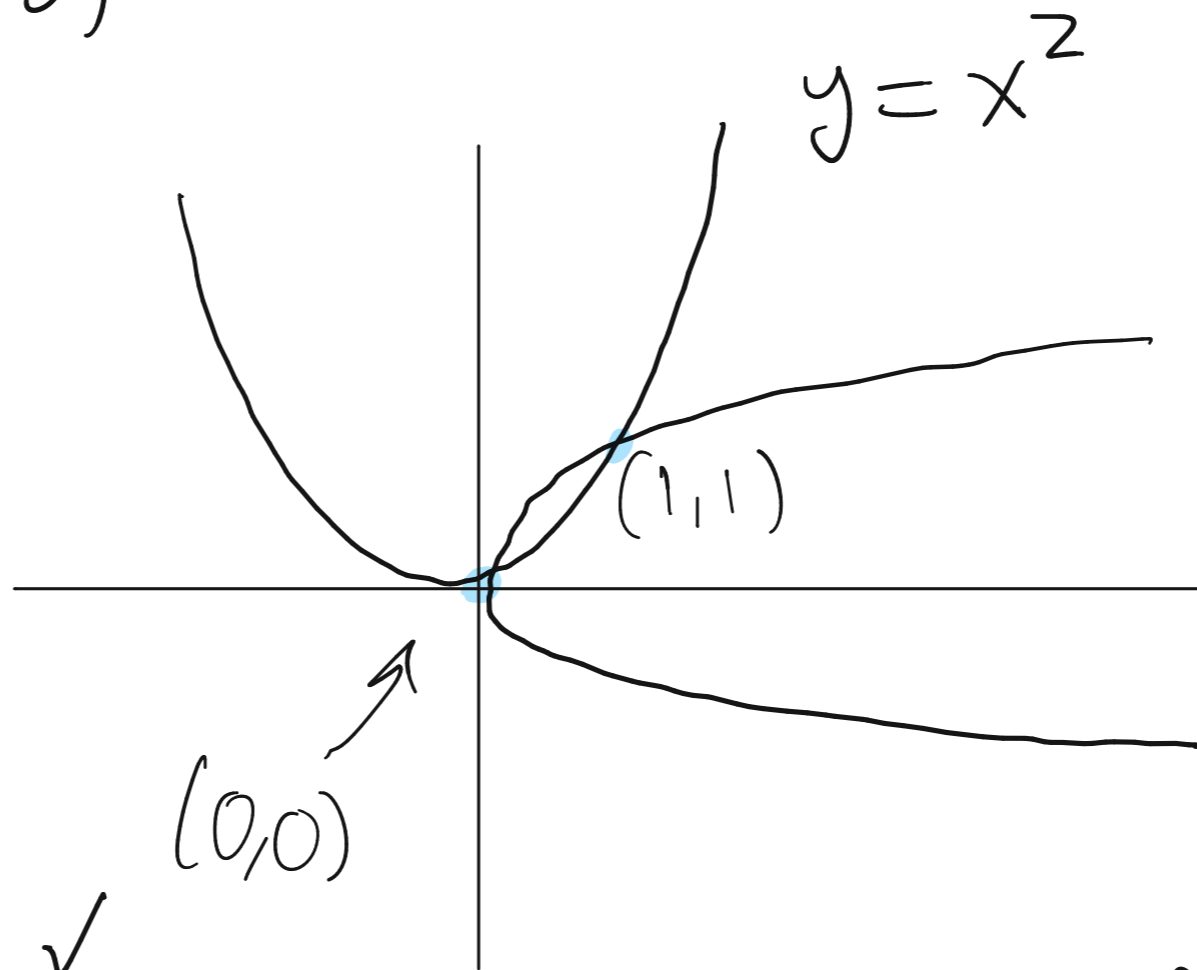
∞<sup>ly</sup> many critical points



$$\sum_x f(x,y) = x^3 + y^3 - 3xy.$$

$$\vec{\nabla} f = \langle 3x^2 - 3y, 3y^2 - 3x \rangle = \langle 0, 0 \rangle.$$

$$\Rightarrow \begin{cases} x^2 = y \\ y^2 = x. \end{cases}$$



Claim:  $\boxed{(0,0), (1,1)}$  are both crit. pts of  $f(x,y)$ .