

Exam 3 is tomorrow!
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Big topics:

Arc length

Vector fields

Line integrals

Parametric Surfaces

flux integrals

Curl

divergence

Green's theorem

Path independence

FTC line integrals

"Standard trick" for parametric curves:

$$y = f(x) \Rightarrow \vec{r}(t) = \langle t, f(t) \rangle$$

$a \leq x \leq b$   $\uparrow$   $t$  bounds  $=$   $x$  bounds  $\uparrow$   $a \leq t \leq b$

$\Sigma x$   $f(x) = x^2 + 3x + 4$   $-3 \leq x \leq 17$

$\updownarrow$

$$\vec{r}(t) = \langle t, t^2 + 3t + 4 \rangle; -3 \leq t \leq 17.$$

$$s = \int_a^b \|\vec{r}'(t)\| dt = \int_a^b \sqrt{(x')^2 + (y')^2 + (z')^2} dt$$

Exam 3 Outline (Motivating Questions)

– 9.8: Arc Length

- How can a definite integral be used to measure the length of a curve in 2- or 3-space?
- Why is arc length useful as a parameter?

→ 12.1: Vector Fields

- What is a vector field? *gradient vector fields, P-I v. fields*
- What are some familiar contexts in which vector fields arise?
- How do we draw a vector field?
- How do gradients of functions with partial derivatives connect to vector fields?



12.2: The Idea of a Line integral

- What is an oriented curve and how can we represent one algebraically?
- What is the meaning of the line integral of a vector-valued function along a curve and how can we estimate if its value is positive, negative, or zero?
- What are important properties of the line integral of a vector-valued functions along a curve?

12.3: Using Parameterizations to Compute Line Integrals



- How can we use a parametrization of an oriented curve  $C$  to calculate  $\int_C \vec{F} \cdot d\vec{r}$ ?
- How does the parametrization chosen for an oriented curve  $C$  alter the value of the line integral  $\int_C \vec{F} \cdot d\vec{r}$ ?
- What can be said about the line integral of a vector field along two different oriented curves when the curves have the same starting point and same ending point?

12.5: Path Independence and FTC for Line Integrals

*gradient v. fields = P.I v. f.s.*

- What characteristic of a vector field  $\vec{F}$  will make  $\int_C \vec{F} \cdot d\vec{r}$  have the same value for every oriented curve from a point  $P$  to a point  $Q$ ?
- What special properties do gradient vector fields have?
- Given a gradient vector field  $\vec{F}$ , how can we efficiently find a potential function  $f$  so that  $\vec{F} = \nabla f$ ?

12.7: The Curl of a Vector Field

- What is meant by rotation of a vector field in a plane?
- How can a two-dimensional measurement of rotation be generalized to work in three dimensions?
- How can the rotational strength of a vector field be measured?

12.8: Green's Theorem

- How can we calculate the circulation of a two-dimensional vector field  $\vec{F}$  around a closed curve when  $\vec{F}$  is not path-independent?

$\mathbb{R}^2$   
only

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_R \text{curl}(\vec{F}) dA$$

*C has to be simple closed curve*

$$\int_C \vec{F} \cdot d\vec{r} = \int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt$$

- What is the meaning of the double integral of the circulation density of a smooth two-dimensional vector field on a region  $R$  bounded by a closed curve that does not intersect itself?

#### 11.6: Surfaces Defined Parametrically and Surface Area

- What is a parameterization of a surface?
- How do we find the surface area of a parametrically defined surface?

#### 12.9: Flux Integrals

- How can we measure how much of a vector field flows through a surface in space?
- How can we calculate the amount of a vector field that flows through common surfaces, such as the graph of a function  $z = f(x, y)$

#### 12.6: The Divergence of a Vector Field

- How can you measure where a vector field is created (or destroyed)?
- How can you measure where a vector field's strength is increasing or decreasing?
- What does the divergence of a vector field measure and how can you visually estimate whether the divergence of a vector field is positive or negative?

$$F = \langle P, Q, R \rangle$$

$$\text{div}(F) = P_x + Q_y + R_z$$

### Exam 3 Outline (Important Concepts and Formulas)

- Arc-length formula
- Reparametrization and arc-length parameterization
- Vector fields
- How to plot a vector field
- Gradient vector fields
- Line integrals with and without using parameterizations
- Work done by a vector field
- Path-independence
- How to tell if a vector field is path-independent
- FTC for Line Integrals
- Potential functions and how to find them
- How to compute curl of a vector field in 2d, 3d
- Interpretations of curl
- What does it mean if  $\text{curl}(\mathbf{F}) = \mathbf{0}$ ? What if curl is non-zero?
- What is a closed curve?
- What is a simply connected region?
- What is a simple closed curve?
- What is Green's theorem and when can we use it?
- Circulation & circulation density of a vector field
- Parametrizations of surfaces
- Common examples:
  - Graphs of functions of the form  $z = f(x, y)$
  - Surfaces of revolution
  - Cylinders
  - Spheres
  - Planes
  - Cones
- Surface area formula from a parameterization
- What is the normal vector of a surface? How is it computed and how do you visualize it?
- What does it mean for a surface to be oriented?
- Flux (i.e. Surface) integrals
- How to compute surface integrals with(out) using a parameterization
- Divergence of a vector field
- Source-free / Divergence-free
- Interpretations of divergence
- Approximation of flux by divergence and small surfaces

Parametric surfaces:

$$z = f(x, y)$$

or

$$y = f(x, z) \quad \text{etc.}$$

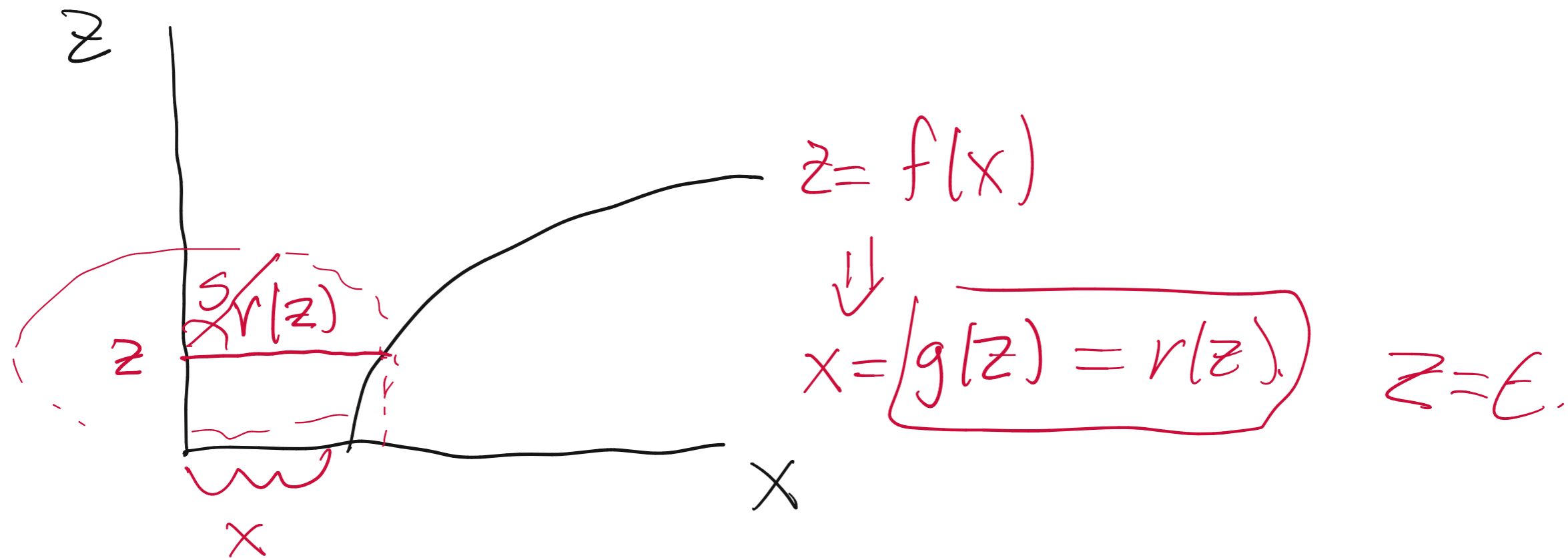
"Std trick"

$$\vec{r}(s, t) = \langle s, t, f(s, t) \rangle$$

$$\vec{r}(s, t) = \langle s, f(s, t), t \rangle \quad y = f(x, z)$$

$$\vec{r}(s, t) = \langle f(s, t), s, t \rangle \quad x = f(y, z)$$

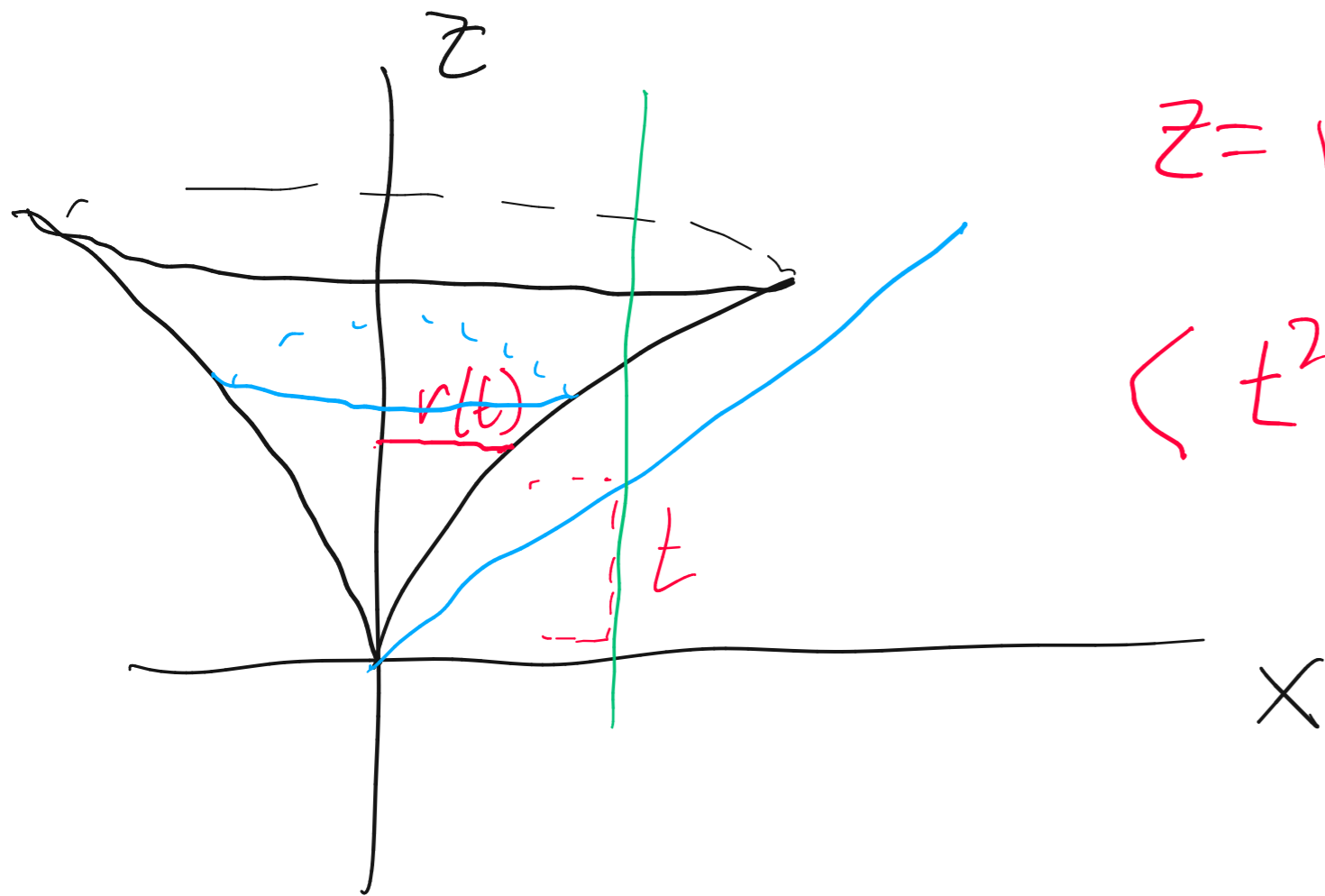
$S$  is a "Surface of revolution".



$$r(s, t) = \left\langle \underbrace{r(t) \cos(s)}, \underbrace{r(t) \sin(s)}, t \right\rangle$$

$$z = \sqrt{x}$$

about  $z$ -axis.



$$z = \sqrt{x} \Rightarrow x = z^2$$

$$\langle t^2 \cos(s), t^2 \sin(s), t \rangle$$

ⓐ height  $t$ , radius =  $t^2$ .



$$\text{flux} = \iint_S \vec{F} \cdot \vec{n} \, dA = \iint F(r(s,t)) \cdot (\vec{r}_s \times \vec{r}_t) \, dA$$